



EUCLID, the planet hunter

Jean-Philippe Beaulieu, Eamonn Kerins & Matthew Penny
Pascal Fouqué, Virginie Batista, Arnaud Cassan,
Christian Coutures & Jean-Baptiste Marquette

Institut d'Astrophysique de Paris
Univ. Manchester
Ohio State University
IRAP Toulouse

Companion talks by Jason Rhodes, Eamonn Kerins & Matthew Penny
WFIRST microlensing : Dave Bennett, Scott Gaudi

Heard several time this week...

There is no microlensing program on board EUCLID

Therefore we should rebrand EUCLID
into...

WONLY

Or even better...

FOR W ONLY

The image features a classic Looney Tunes ending screen. It consists of a series of concentric circles in shades of red and black, creating a tunnel-like effect. In the center, the text "That's all Folks!" is written in a white, elegant cursive script. The text is positioned diagonally across the center of the circles.

That's all Folks!

Heard several time this week...

~~There is no microlensing program on board EUCLID~~

There was a microlensing program on board DUNE (when submitted in 2007)
Dark Energy and microlensing together already in 2007

There is a microlensing program on board EUCLID as part of Legacy Science

ESA Core/Legacy Science

Core science is to understand the origin of the Universe accelerating expansion, probe nature and properties of dark energy, dark matter, gravity

Wide field survey of 15 000 sq deg,
shape and photo z of $2 \cdot 10^9$ galaxies, redshifts of $5 \cdot 10^7$ galaxies.

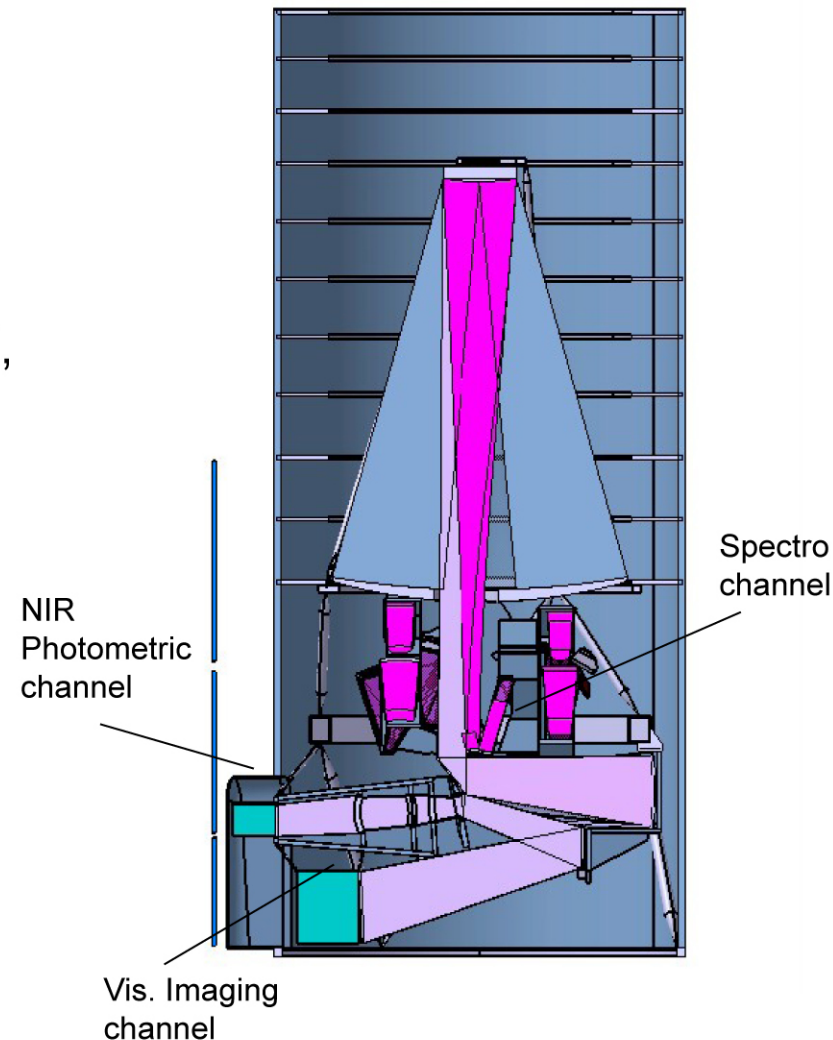
All the rest is Legacy science meaning :

- No constraint on the design of the mission
- Should not be detrimental to core science objective

Microensing is part of the Legacy Science

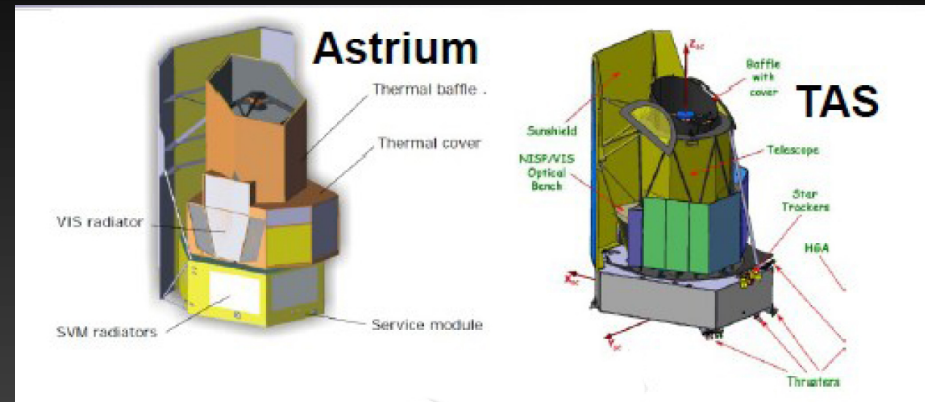
EUCLID spacecraft

- Launch Soyuz, end 2019 L2 Orbit
- 6 years mission
- Telescope: 1.2 m
- Instruments:
 - **VIS:** Visible imaging channel:
 - 0.54 deg², 0.10" pixels, 0.16" PSF FWHM,
 - 1 broad band R+I+Z (0.55-0.92μm),
 - 36 CCD detectors, **galaxy shapes**
 - **NISP:** NIR photometry channel:
 - 0.54 deg², 0.3" pixels,
 - 3 bands Y,J,H (1.0-1.7μm),
 - 16 HgCdTe detectors, **photo-z's**
 - **NISP:** NIR Spectroscopic channel:
 - 0.54 deg²,
 - R(mean)=250,
 - 0.9-1.7μm, slitless, **spectro redshifts**



What's happening now ?

Still two designs in competition :
Selection by ESA in autumn 2012



We do not have full details about the two designs.

Various survey strategy under study in the coming months.

First survey : only core science (estimate gas consumption, efficiency).

Objective : get EUCLID adopted by ESA in June 2012.

Meanwhile/then (in the coming months)

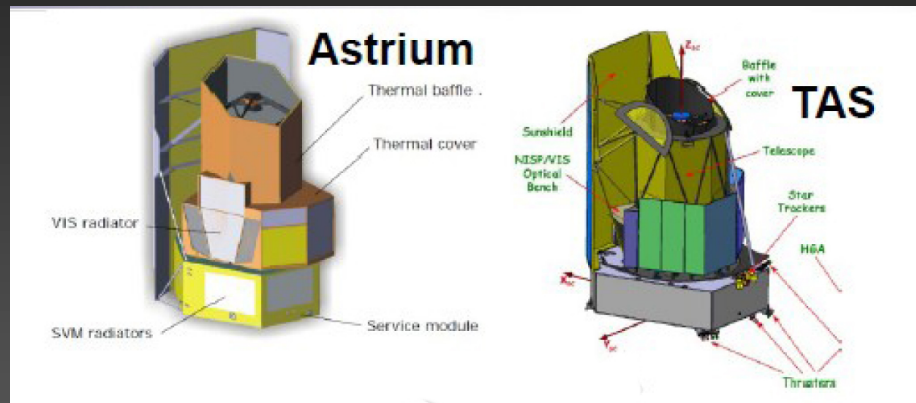
Surveys : incorporating Legacy Science to the core Science.

Time is critical

NISP Photometry exposure time: Y: 100 s, J: 95 s, H 60 s.

NISP Photometry integration time: Y: 121 s, J: 116 s, H 81 s.

VIS exposure time = 565 s



Slew time gaz : 350 sec reaction wheel : 150 sec

Slew time = slew + settling (for cosmic shear requirements)

For H, settling time will be shorter than for VIS but... unknown (to date)

WFIRST small slew goal : 30 sec (less than 60 sec as requirement)...

Sun Avoidance Angle

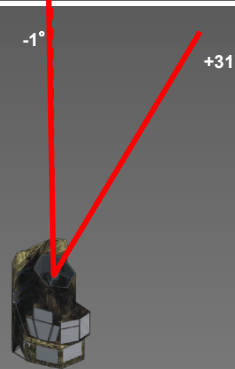
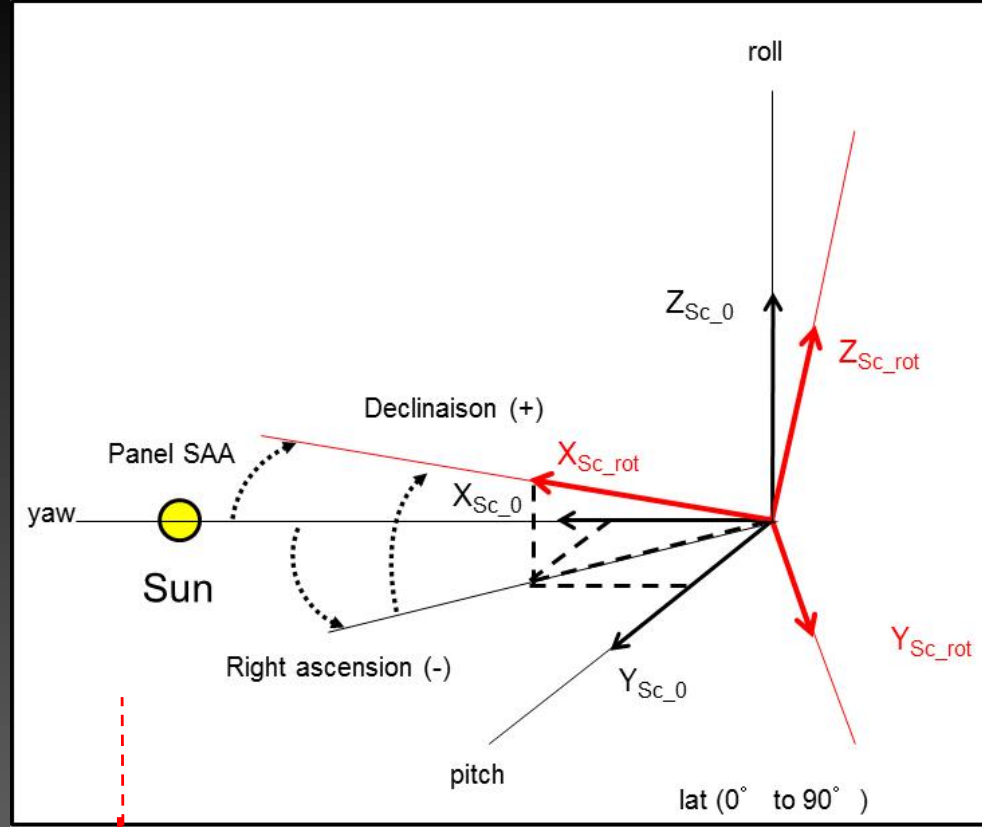
Pointing constraints

The S/C can be operated for a certain range of SAA orientations that limit depointing of the S/C:

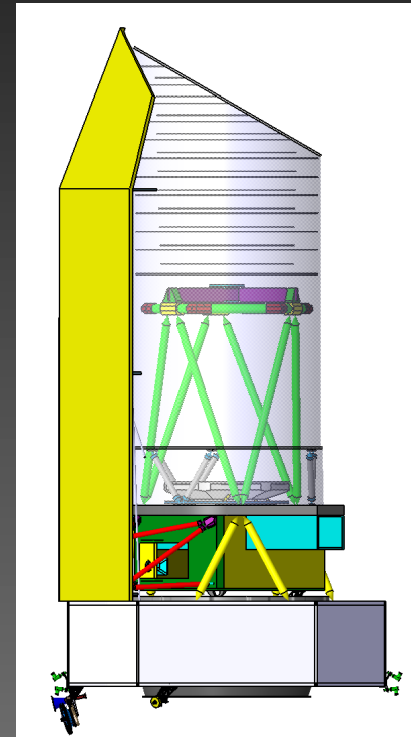
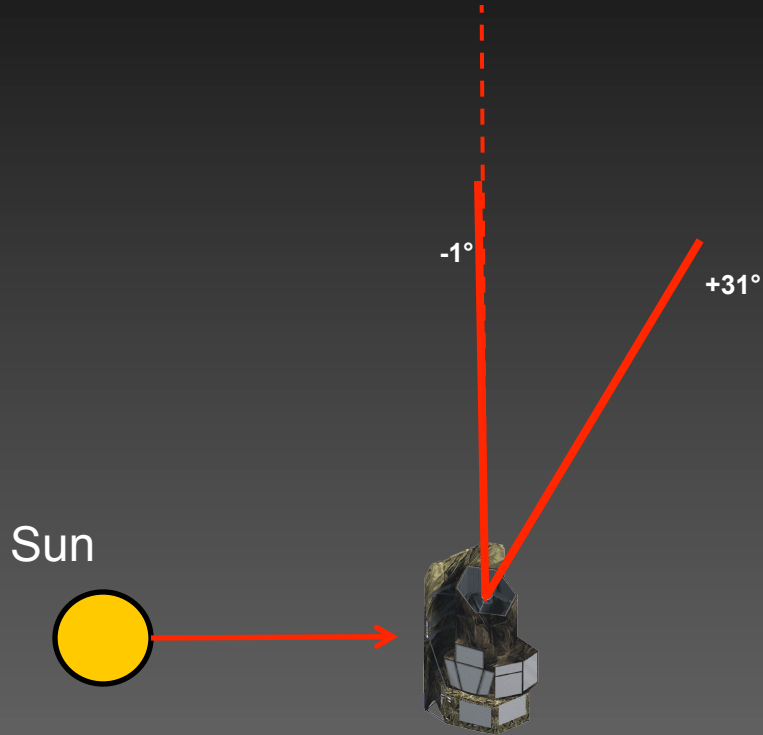
MRD R-440-8: The EUCLID spacecraft shall be able to implement the Deep and the Wide Extragalactic Survey with a variable solar aspect angle included between 89 degrees and 121 degrees.

PSF stability requirements can be ensured for a given range of SAA variation around a reference pointing direction:

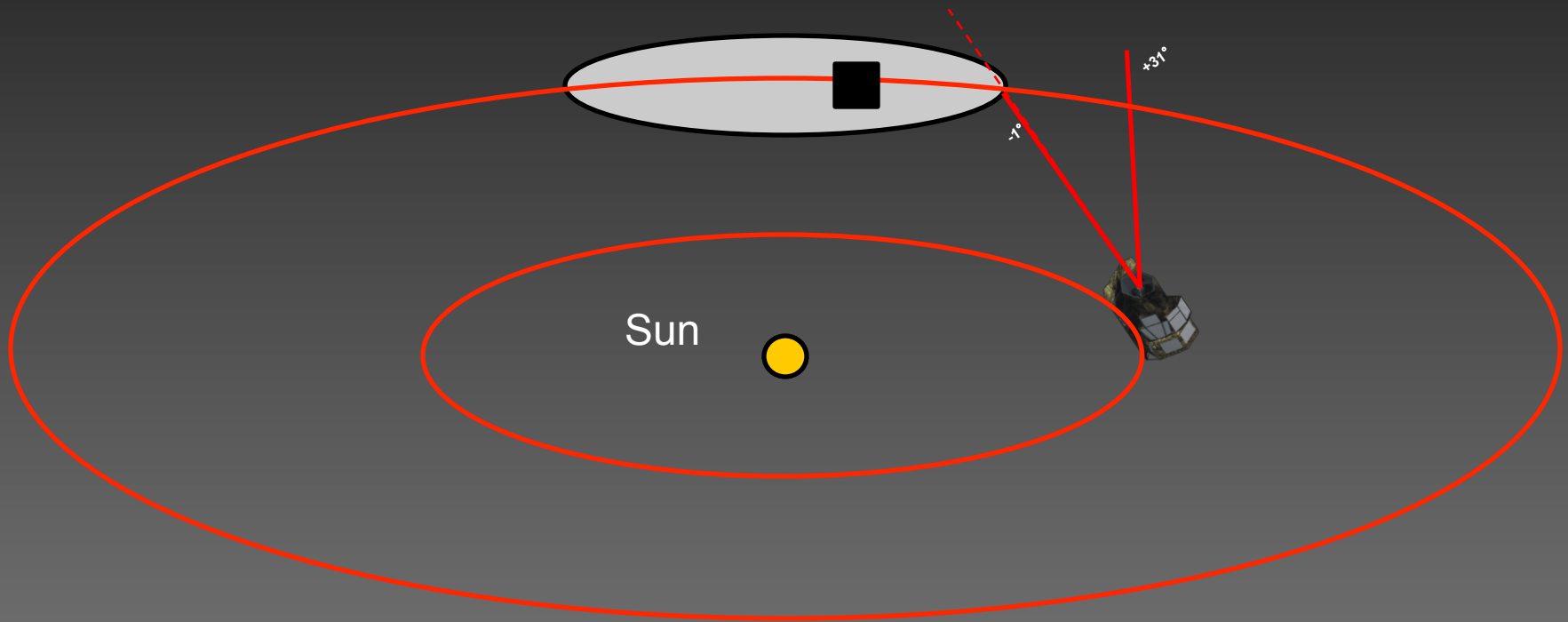
MOCD R-SYS-OP-MS-030: The EUCLID spacecraft shall be able to implement the Deep and the Wide Extragalactic Survey with a variable solar aspect angle included between 90 degrees and 95 degrees.



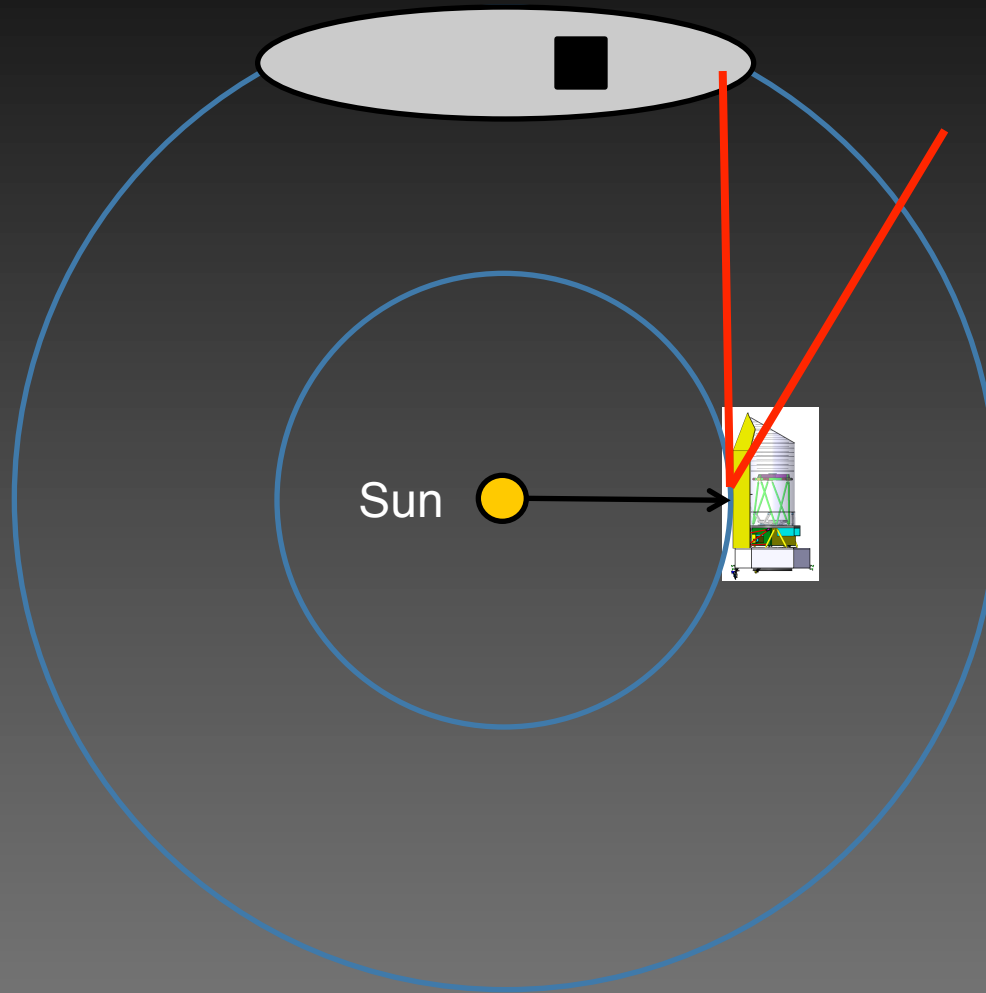
Work Flow for Survey Optimisation



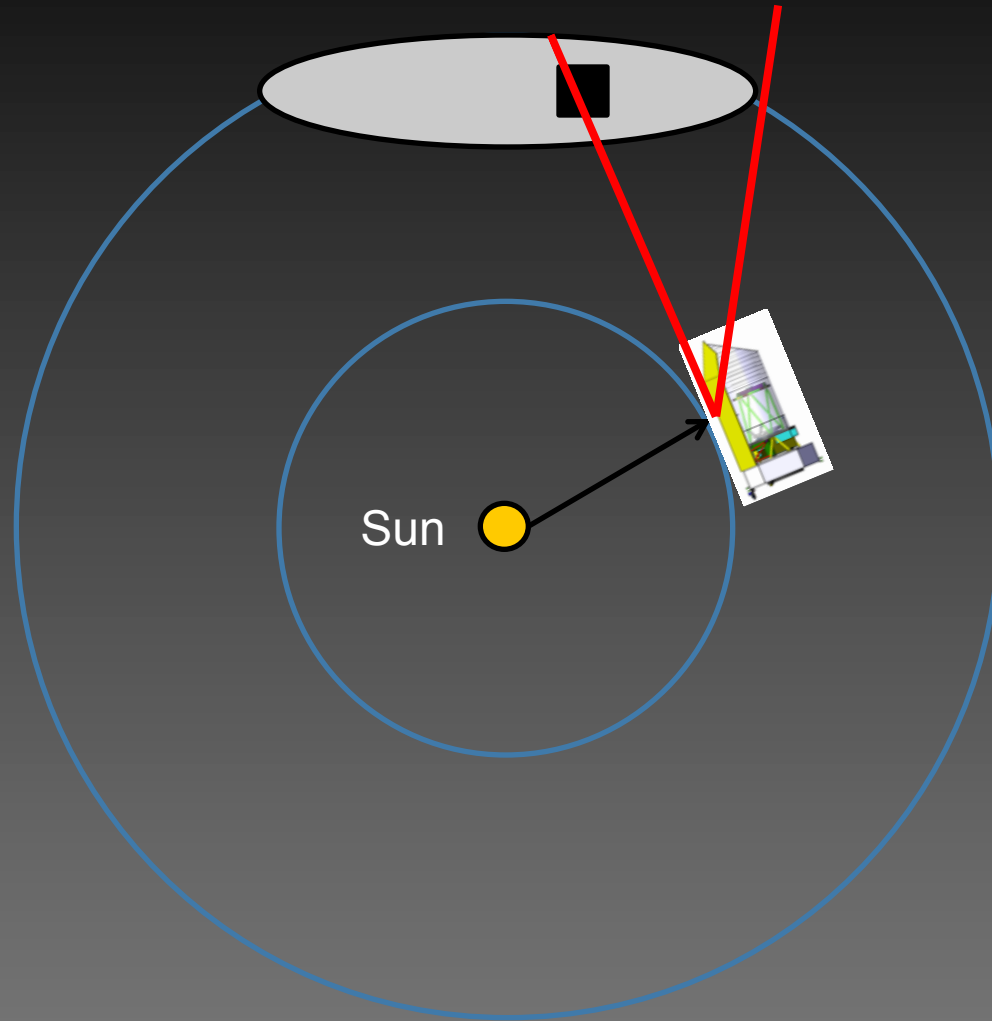
Work Flow for Survey Optimisation



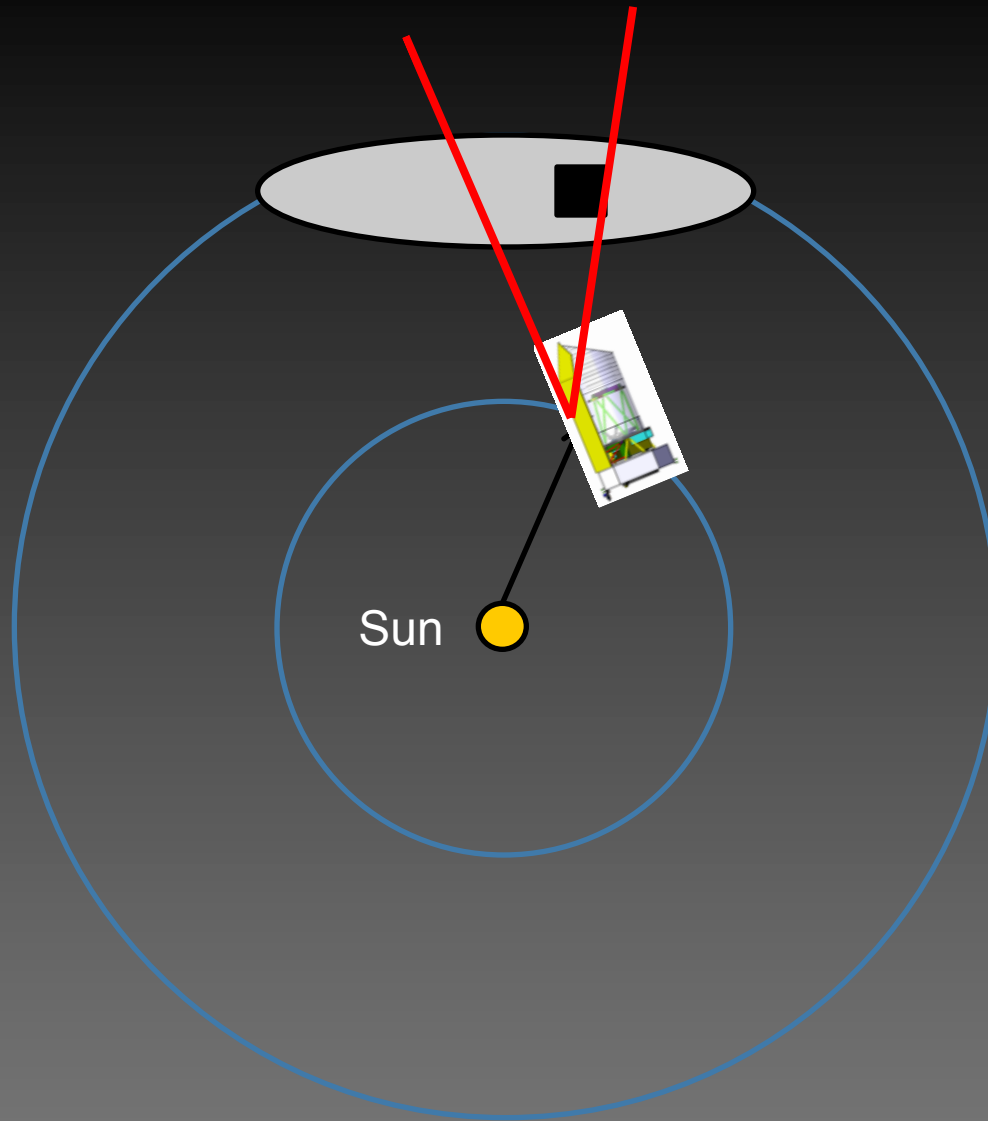
Work Flow for Survey Optimisation



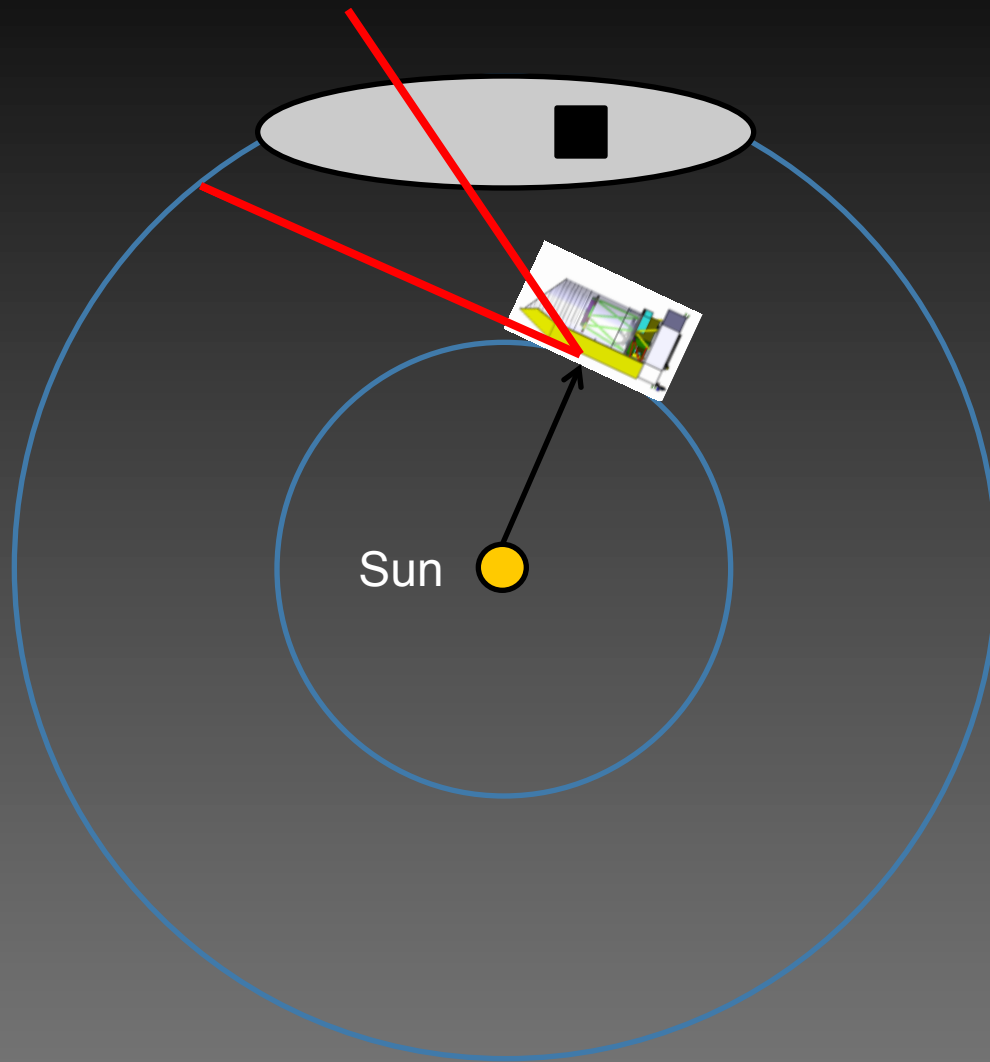
Work Flow for Survey Optimisation



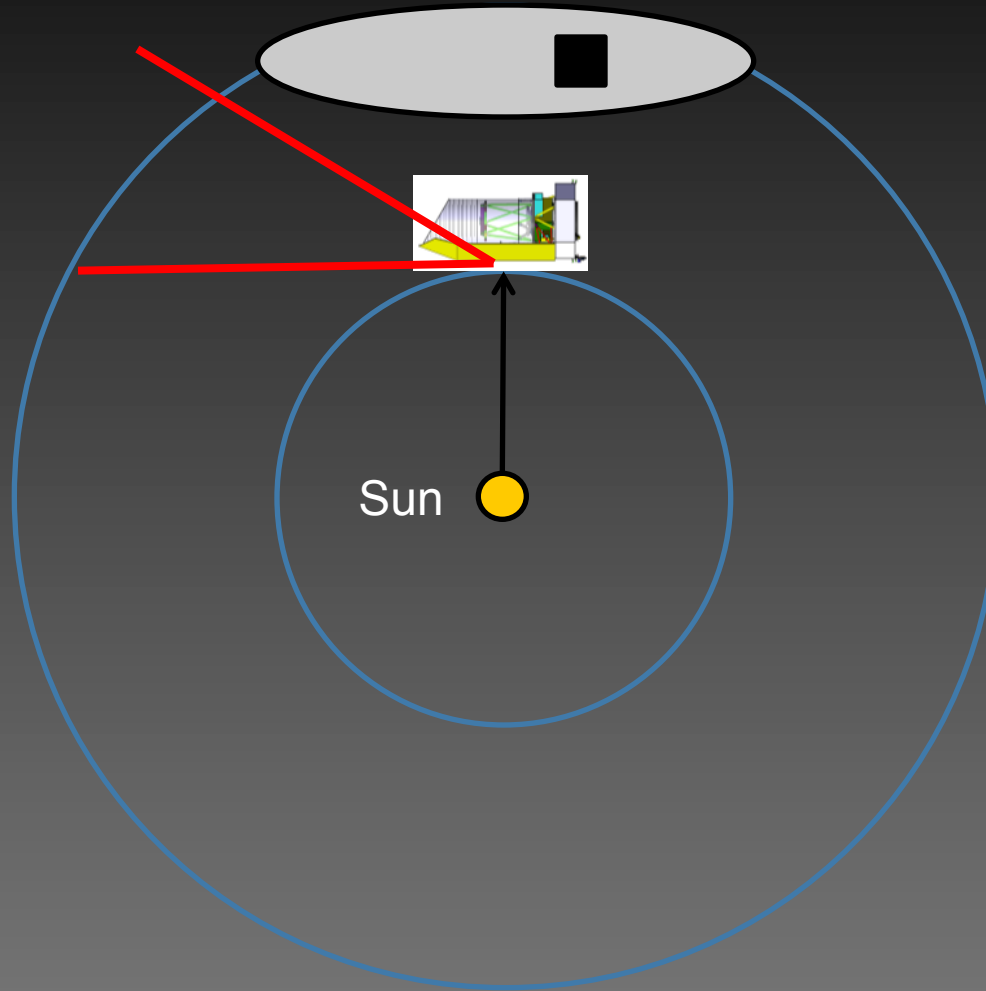
Work Flow for Survey Optimisation



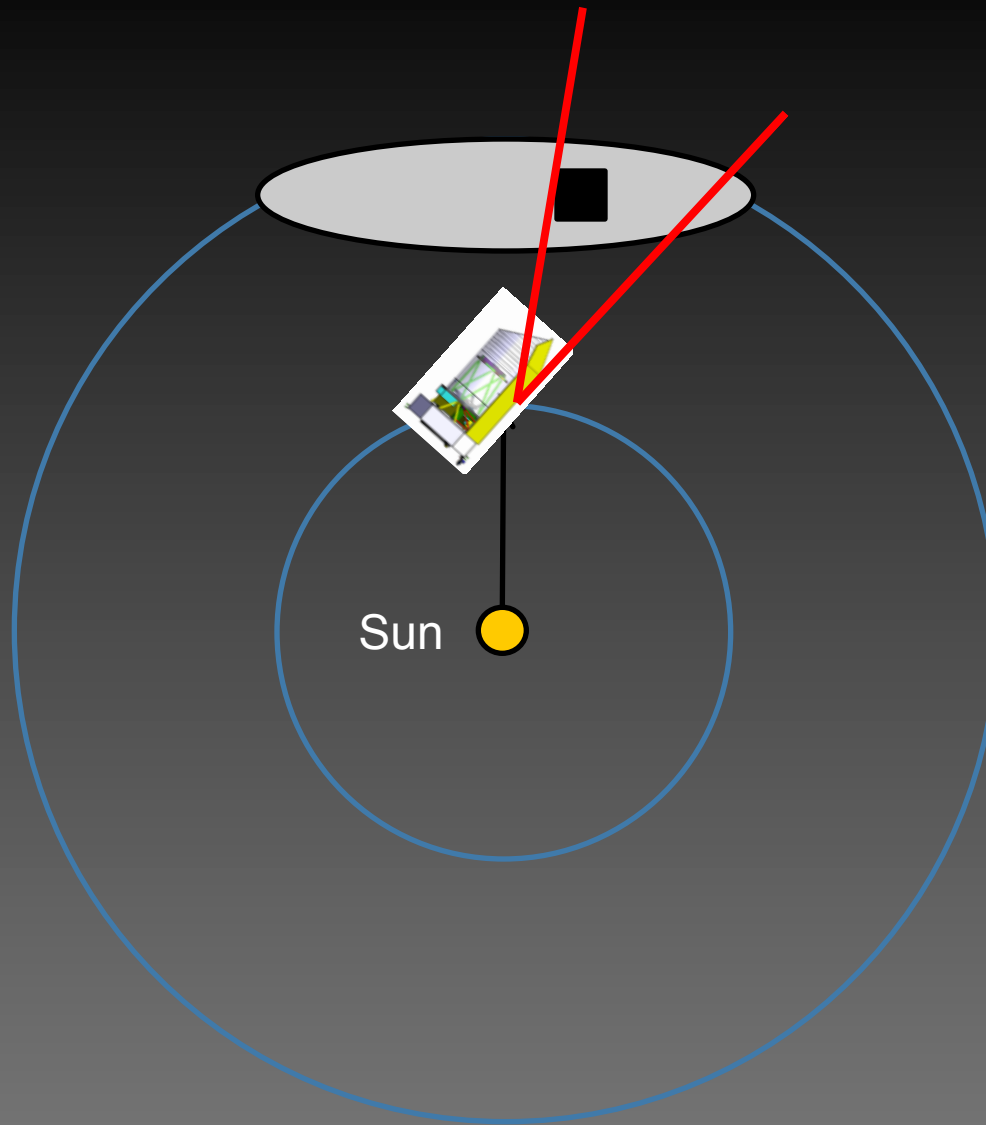
Work Flow for Survey Optimisation



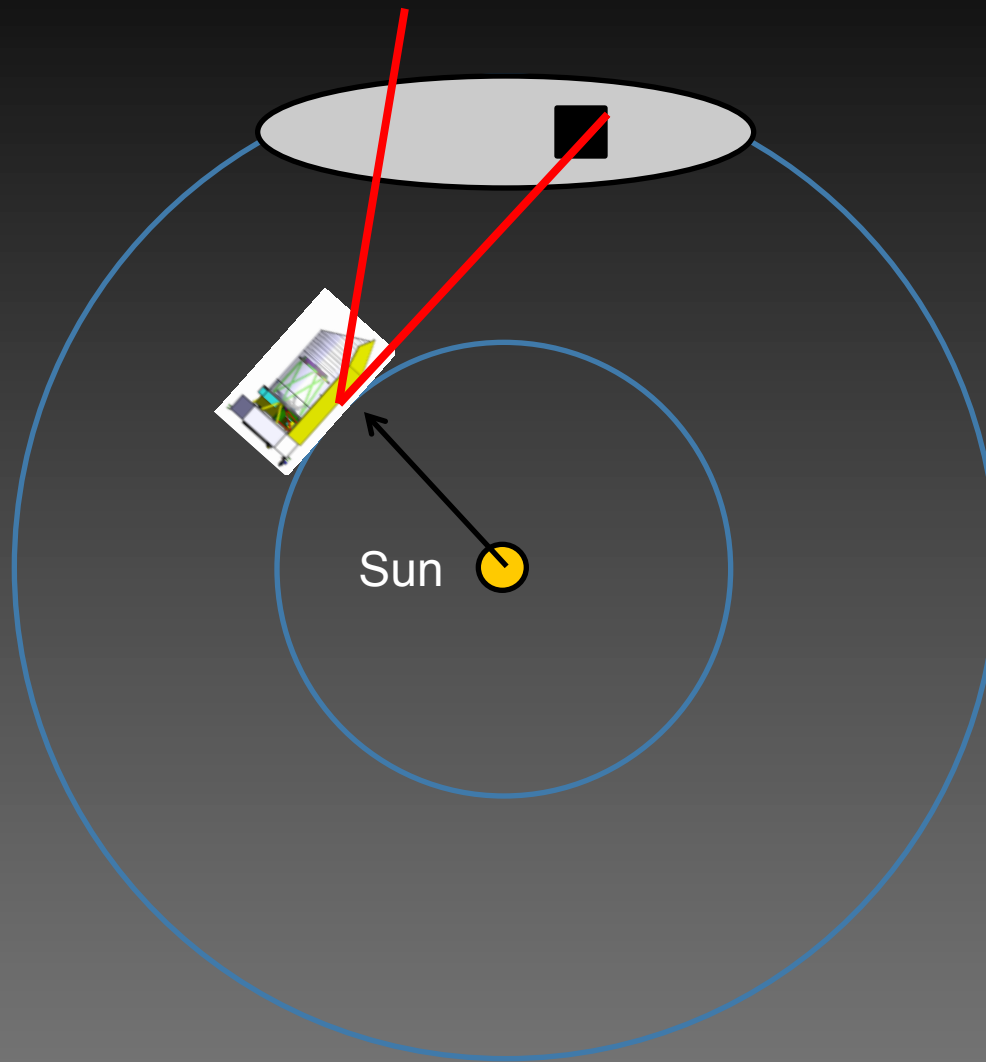
Work Flow for Survey Optimisation



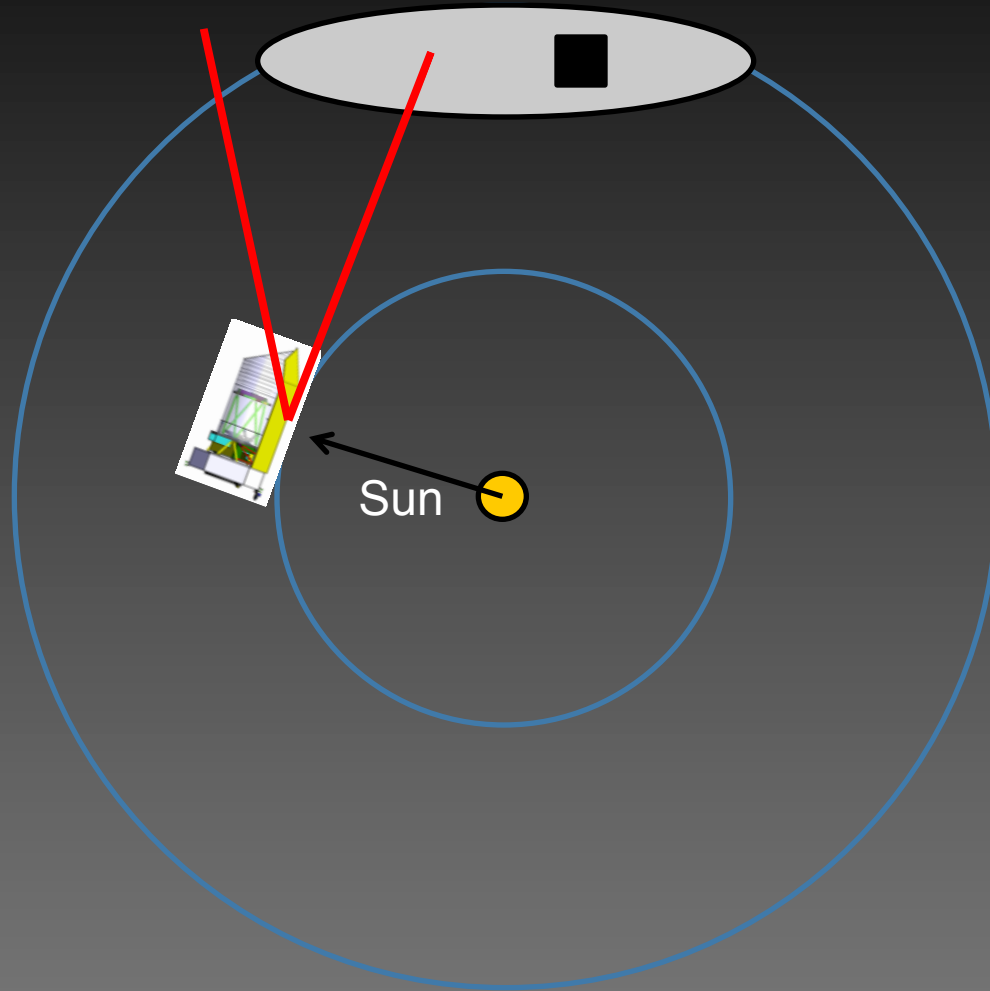
Work Flow for Survey Optimisation



Work Flow for Survey Optimisation



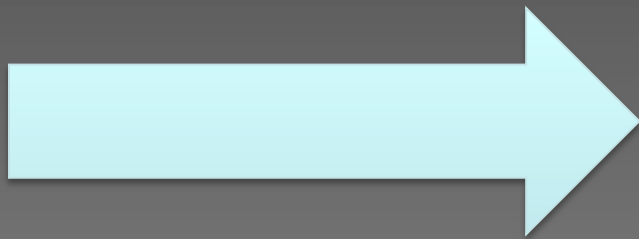
Work Flow for Survey Optimisation



Operation angle from -1 deg to +31 deg.

We can observe for about a month, twice a year.

EUCLID has no contingency for weight : we cannot extend the shielding.



Maximum observation : 2 months/year

Some facts

- Legacy Science status (like all non-DE Science)
- Operation angle from -1 deg to +31 deg
- Slew time 350 sec to 150 sec (settling time for IR unknown).
Probably much better in practice, no official word from ESA
- Maximum observation : 2 months/year
- Implementing Legacy Science surveys with core Science.
--> Simulations + discussions the coming months

EUCLID survey simulation

PhD thesis work of Mathew Penny

Article in prep :

Penny, Kerins, Rattenbury, Robin, Beaulieu MNRAS

Some new calculations will be made very shortly for the paper :

- Updated values of slew times
- Survey in chunks of 1 month instead of 2 month
- Checking the impact of reduced from 2 month to 1 month.
- Potentially adding VISTA data.

MaB μ LS simulator

Diameter (m)	1.2			
Central blockage (m)	0.4			
Slew + settle time (s)	85(285)			
	<i>Detector parameters</i>			
Instrument	VIS		NISP	
Filter	<i>RIZ</i>	<i>Y</i>	<i>J</i>	<i>H</i>
Size (pixels)	24k \times 24k		8k \times 8k	
Pixel scale (arcsec)	0.1		0.3	
PSF FWHM (arcsec)	0.18	0.3*	0.36*	0.45*
Bias level (e ⁻)	380 [†]		380 [†]	
Full well depth (e ⁻)	2 ¹⁶		2 ¹⁶	
Zero-point (ABmag)	25.58*	24.25**	24.29**	24.92**
Readout noise (e ⁻)	4.5	7.5*	7.5*	9.1*
Thermal background (e ⁻ s ⁻¹)	0	0.26	0.02	0.02
Dark current (e ⁻ s ⁻¹)	0.00056 [◇]		0.1*	
Systematic error	0.001 [†]		0.001 [†]	
Diffuse background (ABmag arcsec ⁻²)	21.5 [‡]	21.3 [‡]	21.3 [‡]	21.4 [‡]
Exposure time (s)	540(270)	90	90	54
Images per stack	1	3(1)	3(1)	5(2)
Readout time (s)	< 85		5 [†]	



Besançon model

Microlensing simulator
3 fields, 270 sec per pointing,
5x2 months observing

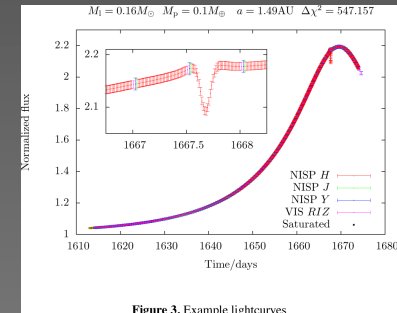
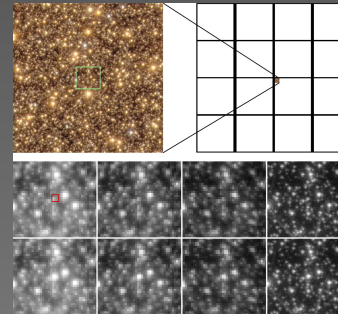
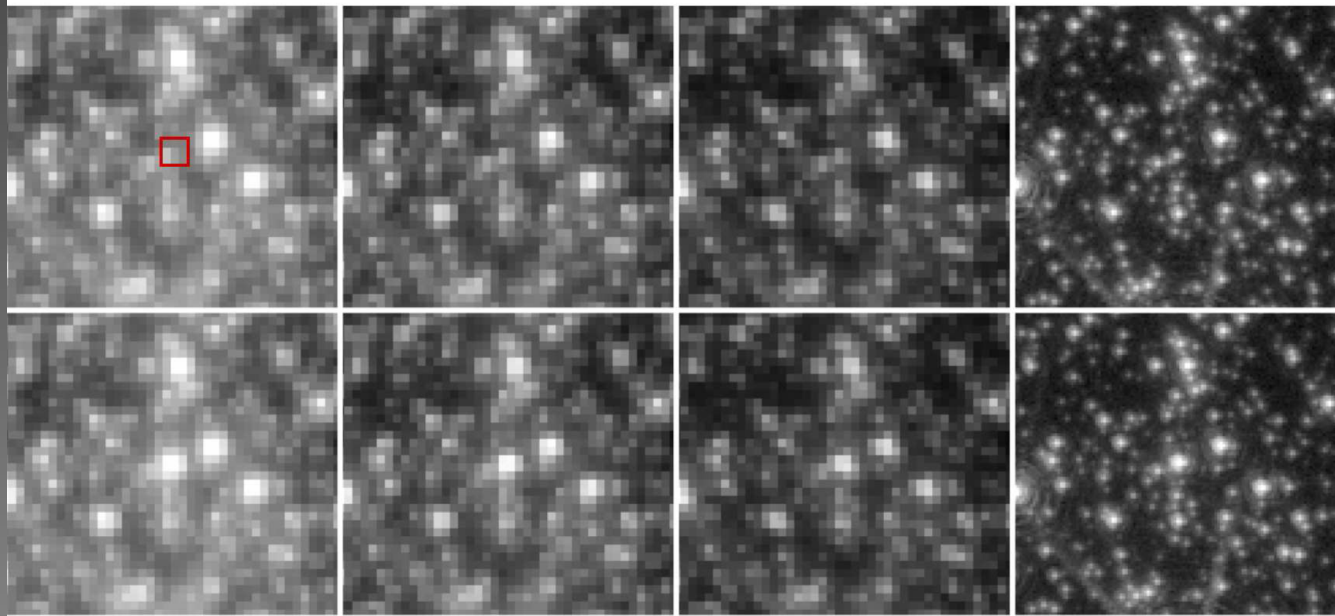
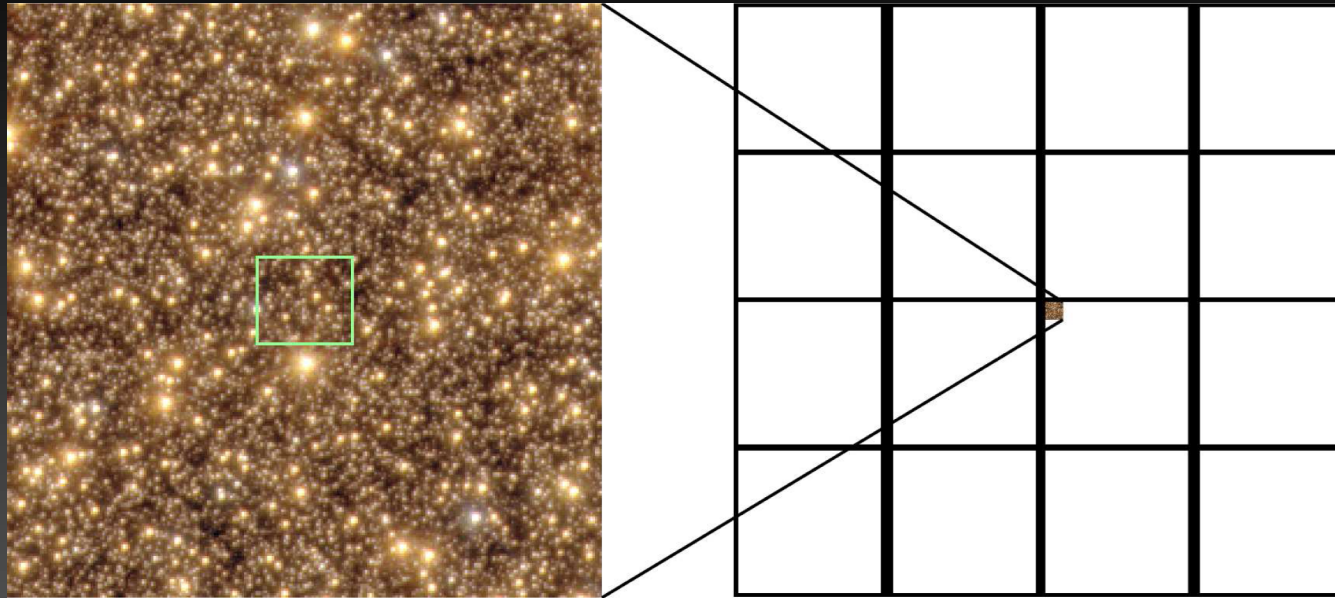


Figure 3. Example lightcurves

Penny, Kerins, Rattenbury, Beaulieu, Robin, 2012, MNRAS in prep
PhD Matthew Penny

Simulated images of galactic Bulge



EUCLID will detect Mars mass planets

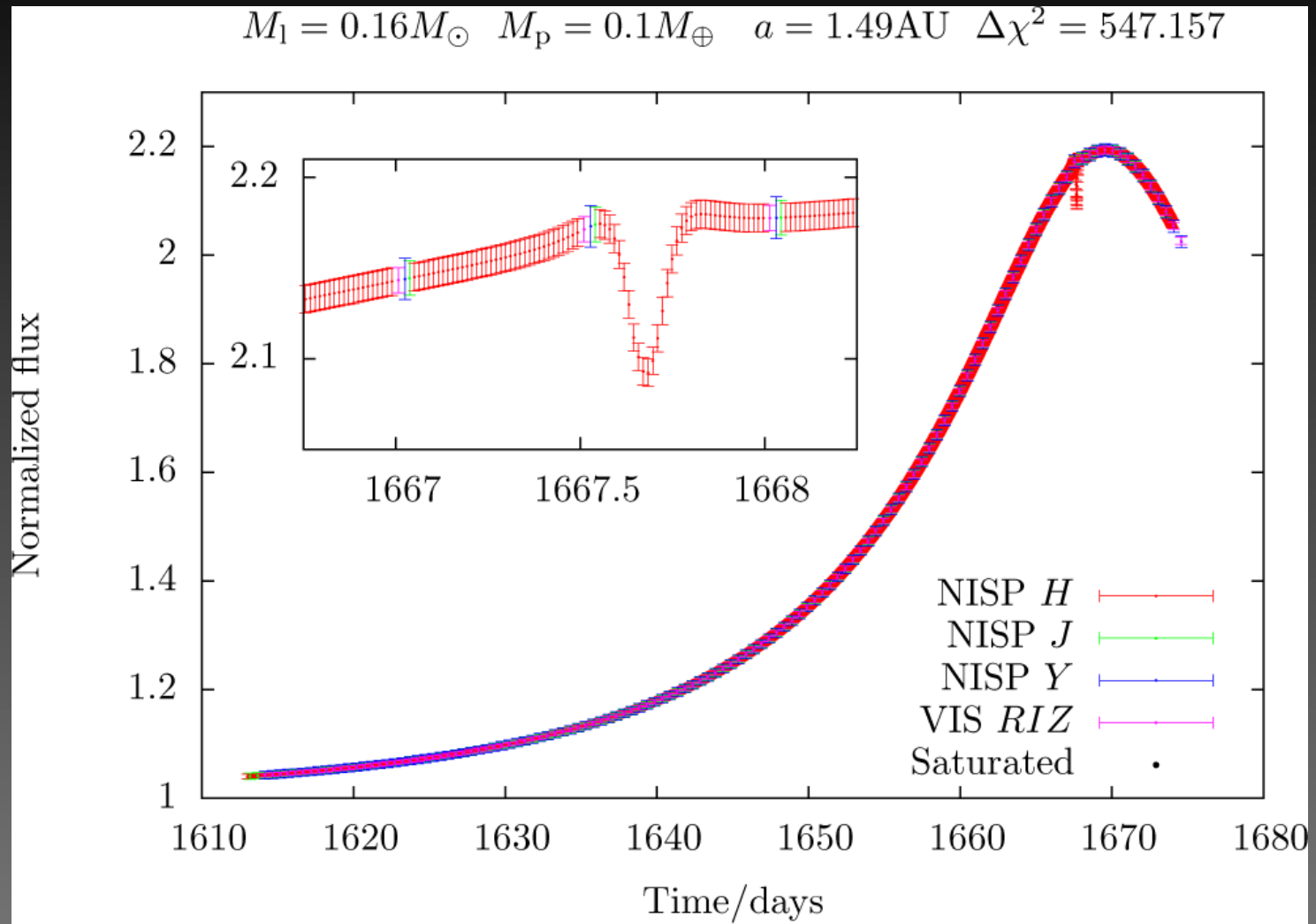
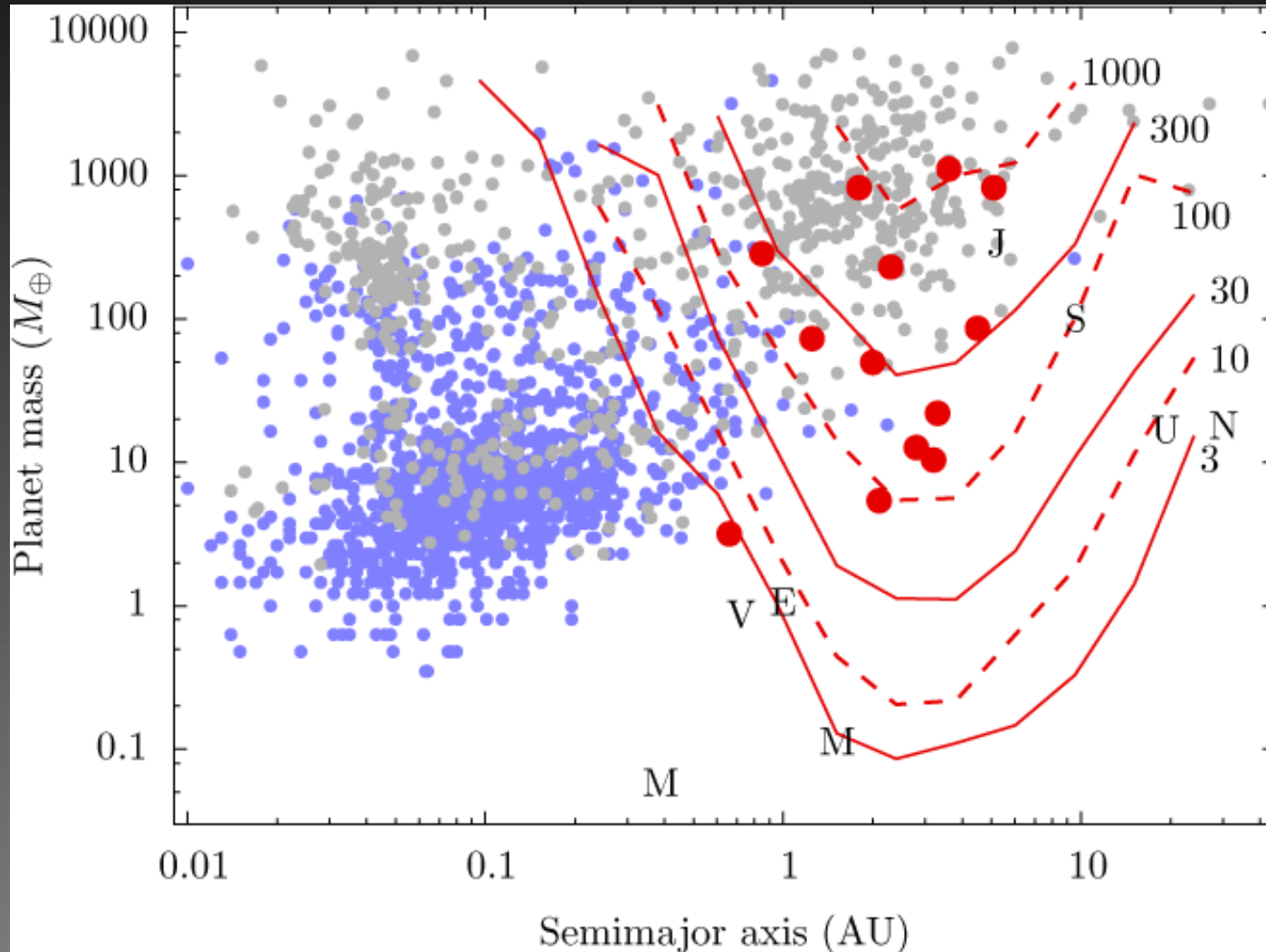
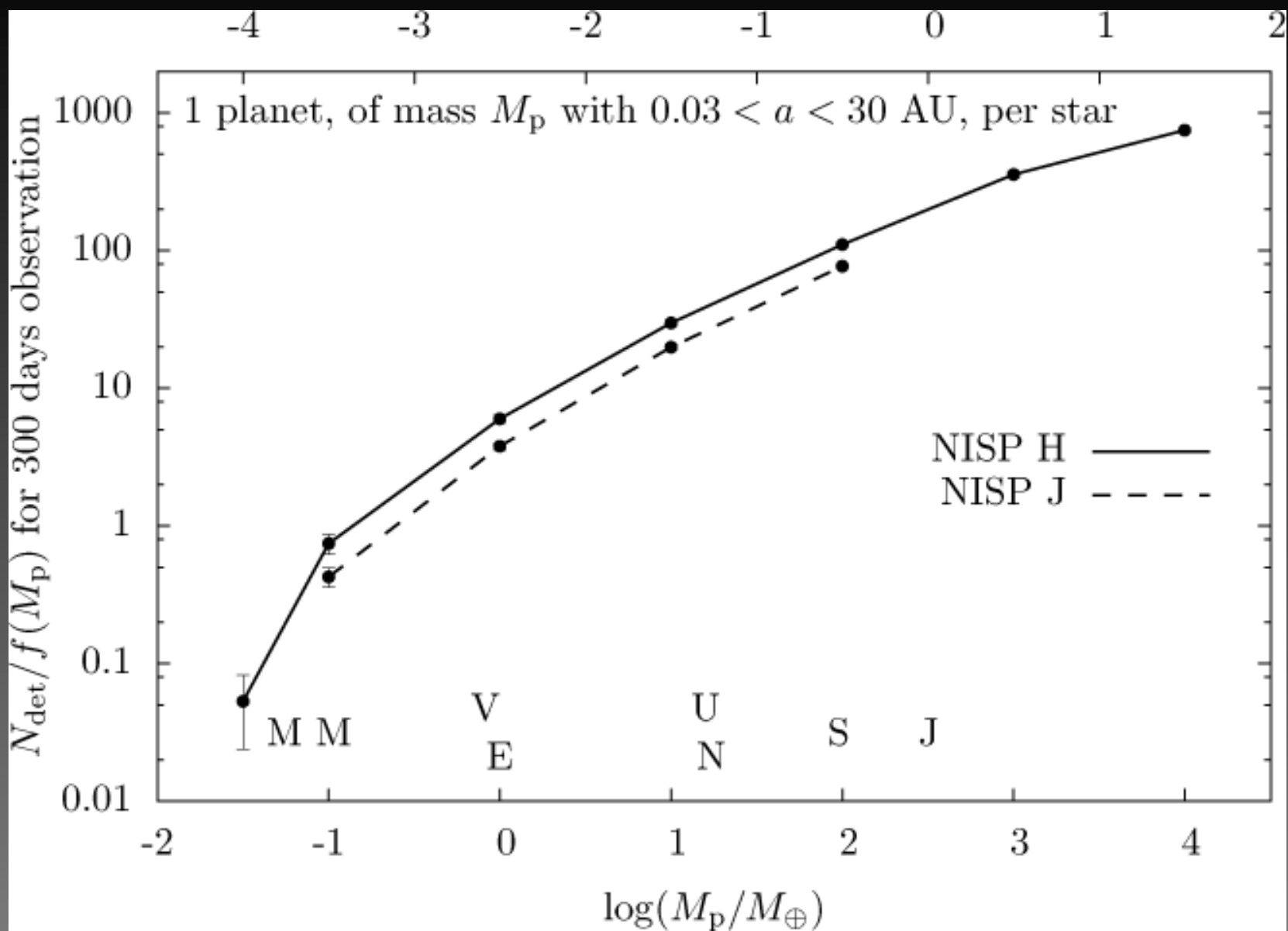


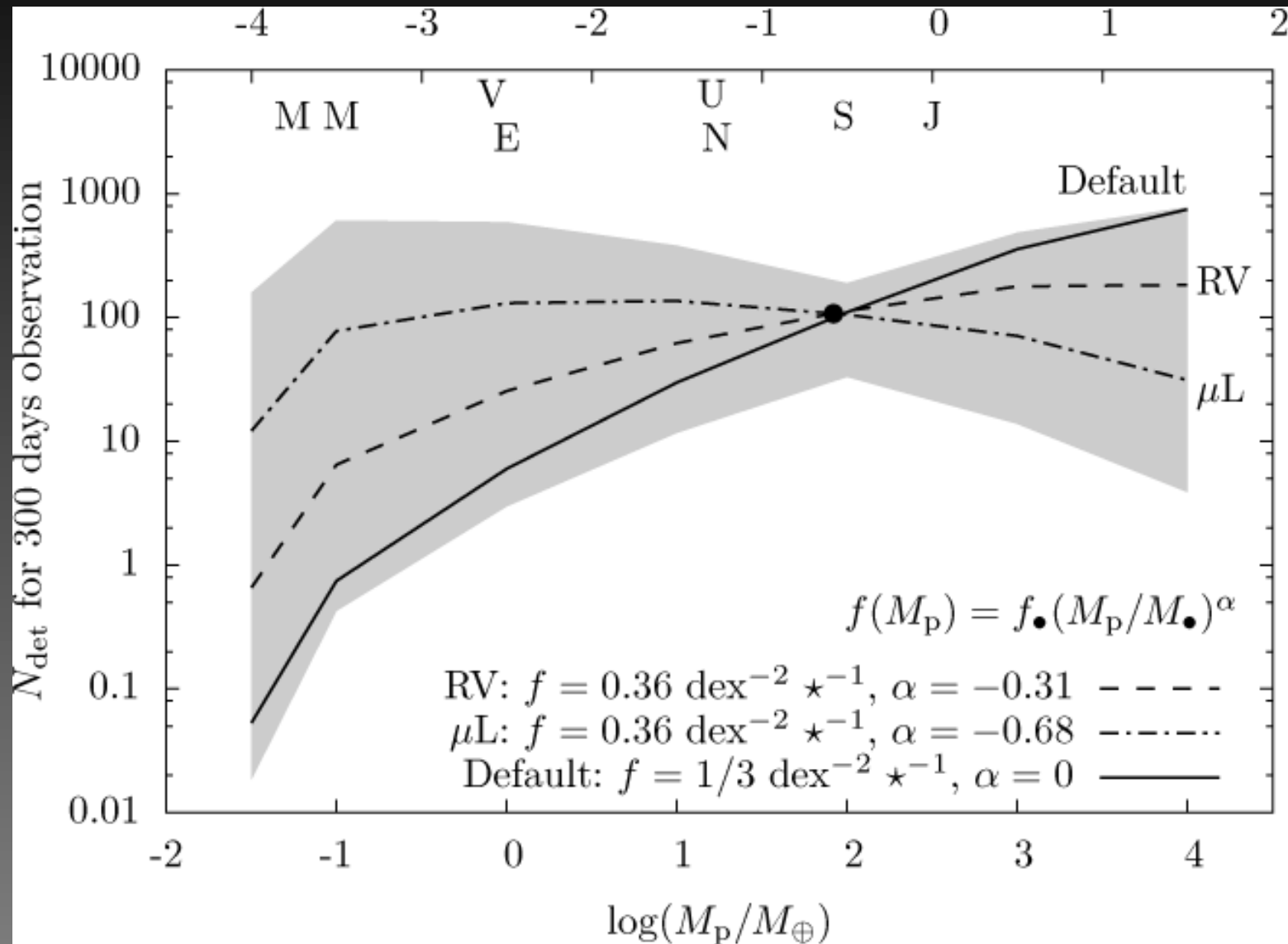
Figure 3. Example lightcurves

EUCLID planet catch with 5x2 months





Measuring the planet mass function



WFIRST science requirements

- A. Make a definitive measurement of the frequency of bound and free-floating planets with masses extending to less than an Earth-mass and separations greater than 0.5 AU.
- B. Measure the masses of the planets and host stars for the majority of the detected exoplanetary systems.
- C. Make a definitive measurement of the frequency of habitable planets

WFIRST & EUCLID

In first approximation :

Planet yields vary linearly with focal plane area & observing time

Measuring Mass requires constraining proper motion :

time span and small pixels.

(ask Jay Anderson)

EUCLID VIS (0.1 arcsec pixel) and H (0.3 arcsec pixel)

Need to have observations spread over the mission.

If WFIRST flies in 2025, a survey done in 2020 with EUCLID will help to constraint the masses !

Conclusion I

Microensing is part of EUCLID Legacy Science

Surveys under studies with Core and Legacy Science (no definitive answer yet)

Rule of thumb : planet yields increases linearly with focal plane area & obs time.

Some EUCLID limitations : operation angle (-1 +30 deg, slew time)

Efficiency of EUCLID Legacy would be greatly increased with US reaction wheels.

We could win time for the surveys !

Early EUCLID microensing observations will help to constraint the masses for WFIRST.

First census on cold planets down to the mass of Mars & free floating planets with EUCLID (6 months).

A more definite survey and η_{EARTH} with WFIRST (or extended EUCLID).

Conclusion II

There is a lot to do now !

- Ground based optical and IR survey (choosing line of sight)
 - OGLE, MOA, KMTNet, VVV, PLANET
 - 2012+, the era of Wide field imagers !
- Developing better image subtraction pipelines
- Improving modeling software (less pedestrian)
- Obtaining landmark results with current ground based facility
- Transition to wide field imager networks (OGLE, MOA, KMTNet, PLANET)
- Maintaining follow up facility (uFUN, RoboNET, PLANET, MINDSTEP)

Conclusion III

To improve the efficiency of EUCLID, reaction wheels would be a tremendous improvement that would free time for Core and Legacy Science.



