

**MOA-2011-BLG-293Lb: A Testbed for Pure Survey  
Microlensing Planet Detections**

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**Abstract:** Microlensing planet searches are transitioning from “survey+followup” mode to “pure survey” mode, wherein events will be monitored without reference to the presence of planets, which will enable a more rigorous statistical interpretation. Such surveys will be able to monitor many more events but at a lower cadence than typical followup observations, meaning that the significance of the planets detected in this manner will be lower. We need a way to test these pure survey detections to ensure that even with sparser data, the planets can be reliably detected. MOA-2011-BLG-293 provides one such test. This planet is robustly detected in survey+followup data ( $\Delta\text{-Chi}^2 \sim 4500$ ). The planet/host mass ratio is  $q=5.1 \pm 0.2 \times 10^{-3}$ . The best fit projected separation is  $s=0.545 \pm 0.005$  Einstein radii, which implies a physical projected separation  $r_{\text{perp}} \sim 1.0$  AU. However, due to the  $s \rightarrow s^{-1}$  degeneracy, projected separations of  $r_{\text{perp}} \sim 3.5$  AU are only marginally disfavored at  $\Delta\text{-Chi}^2=2$ . A Bayesian estimate of the host mass gives  $M_L = 0.44^{+0.27}_{-0.17} M_{\text{Sun}}$ , with a sharp upper limit of  $M_L < 1.2 M_{\text{Sun}}$  from upper limits on the lens flux. Hence, the best estimate of the planet mass is  $m_p=2.4^{+1.4}_{-0.9} M_{\text{Jup}}$ . We show that survey data alone correctly predict this solution and are able to characterize the planet even though the signal from the planet is close to the limit of detectability ( $\Delta\text{-Chi}^2 \sim 500$ ). Analyzing a large sample of events like MOA-2011-BLG-293, which have both followup data and high cadence survey data, will provide a guide for the transition from survey+followup to pure survey microlensing.